

Prediction: Where to Go Next?

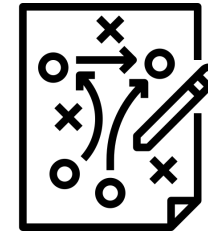
Future Research Directions

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¹Mercedes Benz AG,
work done at KIT, Germany



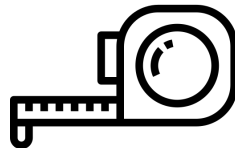
Public Benchmark?



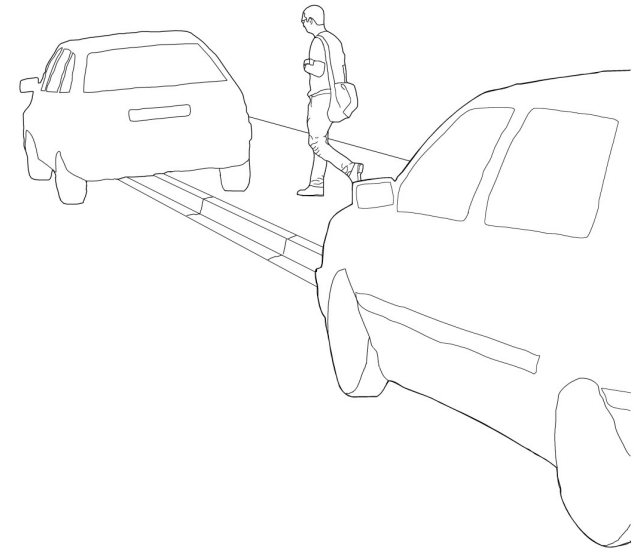
Algorithms?



Dataset?



Metrics?



Icons from <https://www.flaticon.com/authors/monkik>

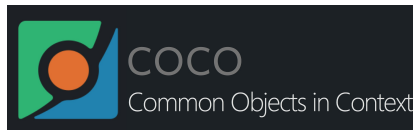
We Need a Public Benchmark!

Public Benchmarks have driven the community [1,2,3,4,5]



**The KITTI Vision
Benchmark Suite**

A project of Karlsruhe Institute of Technology
and Toyota Technological Institute at Chicago



IMAGENET

Given the data and infrastructure, a prediction benchmark is easy to build!

But:

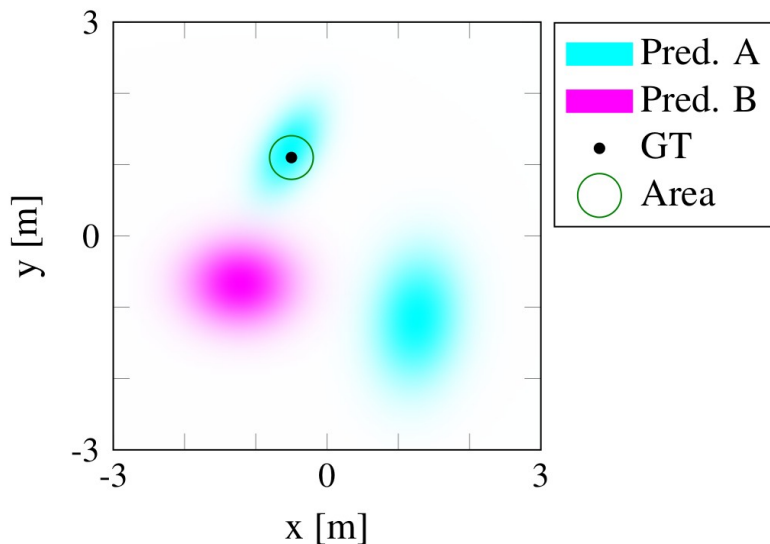
- Data?
- GDPR?
- Metrics?

The one who builds it gets to decide!

We Need Unified Metrics!

Some metrics evaluated for a toy prediction

Example Predictions



Metric	Pred. A	Pred. B
Pred. Prob.	5.8%	0.0%
Log. Pred. Prob.	-2.9	-12.7
Dist.	2.9m	1.9m
AuROC	0.1%	1.2%
AuPR	1.0%	0.2%

Design of metrics put the focus on different traits.
What do you want to measure?

We Need Good Algorithms!

Some example prediction algorithms...



Kalman Filter [6]



CNN [7]

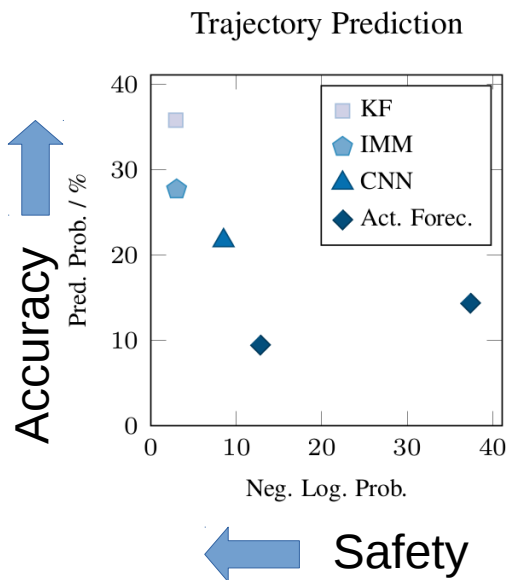


Act. Forec. [8]



MDP* [9]

... and evaluations**



*evaluation work in progress
**preliminary results, data [9]

References

- [1] Everingham, Mark, et al. "The Pascal Visual Object Classes (VOC) Challenge." International Journal of Computer Vision 88.2 (2010)
- [2] Deng, Jia, et al. "Imagenet: A Large-Scale Hierarchical Image Database." IEEE Conference on Computer Vision and Pattern Recognition. (2009)
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- [4] Cordts, Marius, et al. "The Cityscapes Dataset for Semantic Urban Scene Understanding." Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition. (2016)
- [5] Lin, Tsung-Yi, et al. "Microsoft coco: Common Objects in Context." European Conference on Computer Vision. (2014)
- [6] Schneider, Nicolas, and Darius M. Gavrila. "Pedestrian Path Prediction with Recursive Bayesian Filters: A Comparative Study." German Conference on Pattern Recognition. (2013)
- [7] Hoermann, Stefan, et al. "Dynamic Occupancy Grid Prediction for Urban Autonomous Driving: A Deep Learning Approach with Fully Automatic Labeling." International Conference on Robotics and Automation. (2018)
- [8] Kitani, Kris M., et al. "Activity Forecasting." European Conference on Computer Vision. (2012)
- [9] Rehder, Eike, et al. "Pedestrian Prediction by Planning Using Deep Neural Networks." International Conference on Robotics and Automation. (2018)